

#### econ9 PLC i4-100



#### **Description:**

The base controller econ9 PLC i4-100 combines a large number of functions. This functions can be extended by the modular structure of the overall system. The basic version includes multifunctional interfaces, which allow a high flexibility for optimal adaptation to the requirements.

The econ9 PLC i4-100 base controller is also fitted with multiple communication interfaces for easy networking and remote expansion, data can be stored on the optional µSD card permanently.

Variants	PartNo.
econ9 PLC i4-100	10910401
Accessories	PartNo.
Patch Cable, Length 2 m	3030166
CrossOver Cable, Length 2 m	3030167
Backup Battery	2080205
2 GB Micro-SD-Card (max. 32 GB)	6010146
St 2x10pol FMCD 1,5 RM3,5 (terminal clamp for I/O)	2050217
Extensions	PartNo.
in planning	

Functions	Ove	rvie	w C	ODE	SYS	Fir	mwa	are							
CODESYS	Dig I/O	Analog I/O	Interrupt-Inputs	PWM-Outputs	PTO-Outputs	Encoder-Inputs	Fast-Counter-Inputs	CAN / CANopen	RS485	Webvisu	remanent RAM	SD-Card	USB	Ethernet	FTP-Server
econ9 V121	X	X						X	X		X	X	X	X	X

#### Technical Data:

- 1 CAN-Interface
- 1 RS485
- 1 Ethernet-Interface (10/100 Base-T)
- 1 USB 2.0 Host
- 64 MB DDR2 RAM
- 256 MB Nand-Flash
- Backup Battery, Typ CR2032
- Real-time clock
- 2 MB SRAM, battery buffered
- 1 Slot for Micro-SD-Card (microSDHC, max 32 GB)
- $\bullet$  Power supply: 24 V /  $\leq$  1 A DC
- Housing Protection: IP20
- Mounting: DIN Rail DIN EN 60715, 35mm
- Dimension (B x H x T): 53.2 x 110 x 100 mm
- Operating Temperature: 5 ... + 55 °C
- Weight: aprox. 0.2 kg
- Programming Software: CODESYS V3

### **Multifunctional In- / Outputs**

alternatively usable see combination matrix Page 6

- 8 Inputchannels, alternatively usable as
  - 8 digital Inputs 24V 7mA, non isolated, high active
  - 2 Interruptports
  - 2 Incrementalencoderinputs 24V, max. 100 kHz
  - 2 Fast Counter 24V, max. 100 kHz
  - 4 analog Inputs, non isolated 0  $\dots$  +10 V, 12 Bit
- 8 In- / Outputchannels, alternatively usable as
  - 8 digital Inputs 24V 7mA, non isolated, high active
  - 8 digital Outputs 24V 0.5 A, non isolated
  - 2 digital Outputs, PWM/PTO, max. 100 kHz
  - 2 analog Outputs, non isolated 0  $\dots$  +10 V, 12 Bit



CAN 1/2

Pin

#### CAN according to ISO/DIS 11898, isolated

Number of Channels	1
Output Differential Voltage	min. + 1.5 V, max. + 3 V
Input Differential Voltage recessive dominant	min - 1 V, max. + 0.4 V min. + 1 V, max. + 5 V
Input Offset Voltage (versus CAN-GND)	max. +/- 6 V
Input Differential Resistance	min. 20 kΩ, max.100 kΩ
Transmission Rate up to 15 m Cable Length up to 50 m Cable Length up to 150 m Cable Length up to 350 m Cable Length	max. 1 MBit max. 500 kBit max. 250 kBit max. 125 kBit
Number of Subscribers	max. 64
Connecting Cable up to 100 m Cable Length up to 350 m Cable Length	shielded, twisted 0.25 mm <sup>2</sup> 0.5 mm <sup>2</sup>
Recommended Cable Fixed Installation Flexible Installation	UNITRONIC <sup>®</sup> BUS CAN UNITRONIC <sup>®</sup> BUS FD P CAN Twisted Pair

#### **PIN assignment CAN-Interface**



1	nc
2	CAN_L
3	CAN_GND
4	
5	
6	
7	CAN_H
8	
9	



#### **NOTE:**

Termination of the CAN bus via a 120 Ω resistor between CAN\_L (pin 2) and CAN\_H (Pin 7) must be installed in the Sub-D socket of the CAN

## Ethernet, isolated

Number of Channels	1, Twisted Pair (10/100BASE-T)
Transmission according to	IEEE/ANSI 802.3, ISO 8802-3, IEEE802.3u
Transmission Rate	10/100 Mbit/s
Cable Length	max. 100 m
Cable	shielded
Impedance	100 Ω
Plug	RJ45 (Western Plug)
LED – Status Display Yellow Green	Active Link

## PIN-Belegung Ethernet-Schnittstelle



1	TX+
2	TX-
3	RX+
4	GND

Ethernet

Pin



RS485

#### RS485, non isolated

Number of Channels	1
Output Differential Voltage	min. +/- 1.5 V max. +/- 5 V
Input Differential Voltage	min. +/- 0.5 V max. +/- 5 V
Input Offset Voltage (versus GND)	max 6 V/+ 6 V
Output Drive Current Udiff = +/- 1.5 V)	max. +/- 55 mA
Transmission Rate	1200 115200 Bd
Connecting Cable up to 0.14 mm <sup>2</sup> up to 0.25 mm <sup>2</sup>	shielded, min. 0.14 mm² max. 300 m max. 600 m
Termination	by bridging Pin 4 and 5 and Pin 8 and 9, see note

#### PIN assignment R485-Interface

Input Output  To a 2 a a a a a a a a a a a a a a a a a	USB Host
	CO (C.)
Power	Enemet

1	nc
2	
3	
4	Data - (B)
5	Termination -
6	GND
7	
8	Data + (A)
9	Termination +



#### NOTE:

The termination of the RS485 interface has to be done on the both endpoints of the bus **by bridging** the pins 4 and 5 (Data -), and the pins 8 and 9 (Data +), in the Sub-D socket of the RS485 connection cable!

#### **USB 2.0**

Number of Channels	1 x Host (fullspeed)
USB 2.0	USB 2.0 compatible, connector Typ A
Cable Length	max. 5 m
Output Current	max. 0.5 A

## PIN assignment USB-Interface

Irput / Output	
	USB Host
	• Status • Enor
econ <b>9</b>	CAN Err
i4-100	.0
24V 🛊 0V	
Power	Ethernet

1	+ 5V
2	Data -
3	Data +
1	GND

Pin

USB

User Manual econ9 epis 10910401e Rev.: 03

## Data, Acquisition and Control\_

# econ9 PLC i4-100



#### **Power Supply**

Logic supply Rated Value Permissible Range	24 V DC +20 % / -15% plus AC component with peak value of 5% of nominal voltage => 30 19.2 V
Actuator supply Rated Value Permissible Range	24 V 3019.2 V
Sensor supply Rated Value Permissible Range	24 V 3019.2 V
Current Consumption from 24 V	< 1 A for base unit

## **PIN assignment Power Supply**



1	+ 24 V
2	Ŧ
3	0 V

Supply

Pin

## CPU, ARM cortex M4 Processor, memory

Clock Rate	120 MHz
Nand-Flash	256 MB
RAM	64 MB
SRAM	2 MB, battery buffered
μSD-Karte	max. 32 GB

## **Environmental conditions according to EN 61131-2**

Temperature Operating Storage	5 + 55 °C - 25 + 70 °C
Humidity	10 95 % non-condensing
Oscillations	58.4 Hz, const.Ampl. 1.75 mm 8.4150 Hz, Acceleration. 0.5g
Shock	occasional peak values up to 15 g over 11 ms half sine wave
Elevation Operating Storage	up to 2000 m 0 3000 m



#### Real-time clock

Accuracy	
at 25° C	≤ +/- 1 s / Day
at -10 +70° C	≤ + 1 s 11 s / Day

## Backup battery, Lithium - Cell, pluggable

Battery Type	Li 3V / 220mAh CR2032
Backup Time at 20 °C	nom. 5 Years
Recommendation	Battery Change after 2 Years
Battery Change	see User Manual



#### **NOTE:**

To avoid data loss while performing battery change, turn the device on for least 10 minutes prior to change over.

#### **Mechanical Data**

Housing	plastic module housing
Dimensions (B x H x T)	53.2 x 110 x 100 mm
Mounting Method	DIN RAIL 35 mm according DIN EN 60715
Compliance	according DIN 40050 / 7.80
Housing	IP 20
Resistive according to DIN 42115	Alcohol, diluted acid and Alkaline, household cleaner
Weight	aprox. 0.2 kg

# Electromag. compatibility according to EU Directive 2004/108/EG:

## Immunity for industrial environments in accordance with EN 61131-2 / EN 61000-6-2

Electrostatic discharge	EN 61000-4-2
Contact	min. ± 4 kV
Air	min. ± 8 kV
Electromag. RF field ampl.mod.	EN 61000-4-3
80 MHz - 1 GHz	10 V/m 80% AM (1 kHz)
1.4 GHz - 2 GHz	3 V/m 80% AM (1 kHz)
2.0 GHz – 2.7 GHz	1 V/m 80% AM (1 kHz)
Fast transients	EN 61000-4-4
DC network inputs / outputs	± 2 kV
Signal connections	± 1 kV
Surge unbalanced and balanced DC power inputs	EN 61000-4-5 ± 0.5 kV, measured at the AC input of the used AC / DC converter
High-frequency asymmetrical	EN 61000-4-6
0.15 - 80 MHz	10 V, 80% AM (1 kHz)

## Emission standard for industrial areas according to EN 61131-2 / EN 61000-6-4

Radio interference	IEC/CISPR 16-2-3
30 MHz - 1 GHz	40 / 47 dB (μVm)



#### NOTE:

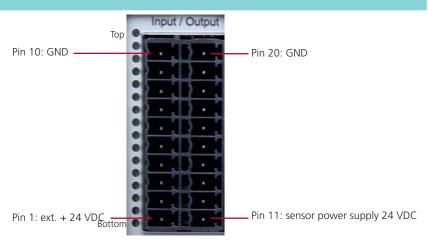
To keep the rules of EMC/CE, a correct and entire construction, according to User Manual, is neccessary.

The manufacturer assembling the system / machine, in which the controller is integrated, is responsible for the electromagnetic compatibility. In order to improve the quality we reserve the rights to change the product.



#### Multifunctionale In-/Outputs







#### Caution:

Reverse voltage on sensor power supply may damage the device!! **Do not bridge Pin1 with Pin11!** 

	combination matrix In- / Outputchannels econ9 PLC i4-100									
Pin/ J1	dig. Input	dig. Output	analog Input 0+10V; 12 Bit	analog Output 0+10V; 12 Bit	Interrupt- input	PWM-Output function blocks: (FB1; FB2)	PTO-Output function blocks: (FB1; FB2)	Encoder- Input function blocks: (FB1; FB2)	Fast-Counter- Input function blocks: (FB1; FB2)	LED
2	10	Q0				PWM0-FB1	PTO0-FB1			Bottom
3	I1	Q1				PWM1-FB1				
4	12	Q2				PWM2-FB2	PTO1-FB2			
5	13	Q3				PWM3-FB2				
6	14	Q4								
7	15	Q5								
8	16	Q6		A00						
9	17	Q7		AO1						
12	18				INT0					
13	19				INT1					
14	I10							CH0A-FB1	Cnt0-FB1	
15	I11							CH0B-FB1		
16	l12		AI0					CH0ldx-FB1		
17	I13		Al1					CH1A-FB2	Cnt1-FB2	
18	114		Al2					CH1B-FB2		
19	I15		AI3					CH1ldx-FB2		Тор



#### Note:

PWM- / PTO-Outputs, Encoderinputs and Fast Counter-Inputs are grouped into functional blocks **FB1** and **FB2**. There is only **1 functionality per function block** possible according to pin assignment.

PWM0 und PWM2 may be used alone.

PWM1 may be used only in combination with PWM0.

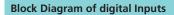
PWM2 may be used only in combination with PWM3.



Input / ENC / IN

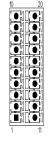
## Digital Inputs / Special Function Inputs, non-isolated

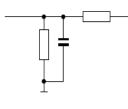
Number of Channels Interruptports Incremental Encoder Inputs Timer- / Counter-Inputs Analog Inputs	8, usable as 2 2 2 4 (see below)
Supply Voltage Rated Value Permissible Range	24 V - 30 + 30 V
Input Current at Nominal Voltage (24 V)	6.3 mA
Input frequency at duty cycle 0.5	≤ 100 kHz
Delay Time Standard Inputs tLOW - HIGH tHIGH - LOW	2 μs 2 μs
Input Voltage LOW - Level HIGH - Level	≤ 5 V ≥ 15 V
Input Current LOW - Level HIGH - Level	≤ 1.5 mA ≥ 3 mA
Input Impedance	3.8 kΩ
Sensor Suppply (Output)	24 V DC, max. 200 mA
when using as Incremental encoder Inputs	
Input signals	2-Phases-Rectangle moved about 90°, 1 Zero Impulse
Signal Evaluation	quadruple



## 11 +24 V Sensor Power Supply (Output)

Pin/J1





11	+24 V Sensor Power Supply (Output)
12	18 / INTO
13	19 / INT1
14	I10 / CH0A-FB1 / Cnt0-FB1
15	I11 / CH0B-FB1
16	I12 / CH0ldx-FB1
17	I13 / CH1A-FB2 / Cnt1-FB2
18	I14 / CH1B-FB2
19	I15 / CH1ldx-FB2
20	GND

## Analog Inputs, non-isolated

4
0 +10 V
ADC successive approximation 12 Bit 7 µs 935 Hz
0 +15 V
90.8 kΩ
≤ + 30 mV
+/- 1%
shielded max. 10 m
C

## **Block Diagram of analog Inputs**

	11	+24 Pov (
	16	
<b>†</b>	17	
	18	
1	19	

11	+24 V Sensor Power Supply (Output)
16	Al0
17	Al1
18	Al2
19	Al3
20	GND

AIN

Pin/J1



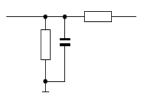
Input

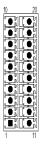
Pin/J1

## Digital In- / Outputs / Special Function Inputs, non-isolated

Number of Channels	8
uses as digital Inputs	8
Input Voltage Permissible Range	24 V - 30 + 30 V
Input Current HIGH – Level	6.4 mA
Delay Time tLOW – HIGH tHIGH - LOW	1.5 ms 1.9 ms
Threshold ULOW – HIGH UHIGH - LOW	≤ 5 V ≥ 15 V
Input Impedance	3.8 kΩ
used as digital Outputs	see page 9

## **Block Diagram of digital Inputs**





1	ext. + 24 VDC
2	10
3	I1
4	12
5	13
6	14
7	15
8	16
9	17
10	GND



#### Caution

Reserve current at the outputs may damage the output stage!



ext. + 24 VDC

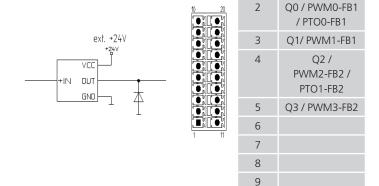
**GND** 

Output

## Digital In- / Outputs / Special Function Inputs, non-isolated

Number of Channels	8
used as Digital-Eingänge	see page 8
used as digital Outputs	4
Load Voltage Vin Nominal Value Permissible Range	24 V 18 30 V
Output Voltage HIGH – Level LOW – Level	min. $V_{in}$ – 0.39 V max. 2 $\mu$ A x R <sub>Last</sub>
Short Circuit Protected	yes, thermal Overload Protection
Output Current	0.5 A DC
Parallel switching of Outputs	no
Utilization factor	100%
used as PWM/PTO Output	2
Output Current	0.5 A DC
Short Circuit Protected	yes, thermal Overload Protection
Switching Frequency standard Output resistive load inductive load	100 kHz 100 kHz
Simultaneous Factor	100%

Block Diagram of digital Outputs 0.5 A or of PWM/PTO Outputs	Pin/J1	Output





#### Note:

PWM- / PTO-Outputs, Encoderinputs and Fast Counter-Inputs are grouped into functional blocks **FB1** and **FB2**. There is only **1 functionality per function block** possible according to pin assignment.

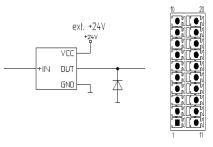
PWM0 und PWM2 may be used alone.

PWM1 may be used only in combination with PWM0. PWM2 may be used only in combination with PWM3.

#### Digital In- / Outputs / Special Function Inputs, non-isolated

Number of Channels	8
used as Digital-Eingänge	see page 8
used as digital Outputs	4
Load Voltage Vin Nominal Value Permissible Range	24 V 18 30 V
Output Voltage HIGH – Level LOW – Level	min. V <sub>in</sub> – 0.07 V max. 5 µA x R <sub>Last</sub>
Output Current	0.5 A DC
Parallel switching of Outputs	possible, max. 4 Outputs
Short Circuit Protected	yes, thermal Overload Protection
Switching Frequency standard Output resistive load inductive load	100 Hz 2 Hz (depends on inductivity)
Lamp load	max. 6 Watt
Utilization factor	100%

## **Block Diagram of digital Outputs 0.5 A**



1	ext. + 24 VDC
2	
3	
4	
5	
6	Q4
7	Q5
8	Q6
9	Q7
10	GND

Pin/J1



#### **Caution:**

Reserve current at the outputs may damage the output stage!

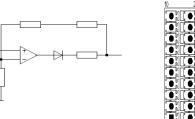


**AOUT** 

## **Analog Outputs, non-isolated**

Number of Channels	2
Output Area Voltage Range	Voltage 0 +10 V
DA Change Principle Resolution Load Conversion Time max. Frequency	R2R 12 Bit max. 5 mA ≤ 100 µs aprox. 5 kHz
Offset Error (0-Point)	≤ +/- 30 mV
Gain Error	≤ <b>+/-</b> 0.5%
Connection Cable length	shielded max. 10 m

## **Block Diagram of analog Outputs**

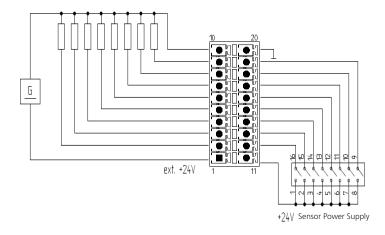


1	ext. + 24 VDC
8	A00
9	AO1
10	GND

Pin/J1

## Wiring example

Digital In - / Outputs (here 8E/8A)





#### Caution:

Reseve voltage on sensor power supply may damage the device!! **Do not bridge Pin1 with Pin11!** 



#### **Caution:**

Reserve current at the outputs may damage the output stage!